

Divergents, rotationnels, gradients

Laplacien de U : $\Delta U = \frac{(\partial U)^2}{\partial x^2} + \frac{(\partial U)^2}{\partial y^2} + \frac{(\partial U)^2}{\partial z^2}$

$$\overrightarrow{\text{Grad}} \vec{U} = \begin{vmatrix} \frac{\partial U}{\partial x} \\ \frac{\partial U}{\partial y} \\ \frac{\partial U}{\partial z} \end{vmatrix} \quad \overrightarrow{W} = \overrightarrow{\text{Rot}} \vec{V} \quad \vec{V} = \begin{vmatrix} P \\ Q \\ R \end{vmatrix} \Rightarrow \vec{W} = \begin{vmatrix} P_1 = \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \\ Q_1 = \frac{\partial P}{\partial x} - \frac{\partial R}{\partial x} \\ R_1 = \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \end{vmatrix}$$

$$\text{div} \vec{W} = \vec{\nabla} \cdot \vec{V} \quad \overrightarrow{\text{Rot}} \vec{V} = \vec{\nabla} \wedge \vec{V} \quad \vec{V} = \begin{vmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{vmatrix}$$

$$\overrightarrow{\text{Rot}}(\overrightarrow{\text{Grad}} \vec{V}) = 0 \quad \text{div}(\overrightarrow{\text{Rot}} \vec{V}) = 0 \quad \text{div}(\overrightarrow{\text{Grad}} \vec{V}) = \Delta U \text{ (Laplacien)}$$

$$I_S = \iint_S \Omega = \iint_S [P_1 dy \wedge dz + Q_1 dx \wedge dz + R_1 dx \wedge dy]$$

$$\omega = P dx + Q dy + R dz \quad d\omega = dP \wedge dx + dQ \wedge dy + dR \wedge dz$$

$$\text{Prod. ext.: } \omega_1 = P_1 dx + Q_1 dy + R_1 dz \quad \omega_2 = P_2 dx + Q_2 dy + R_2 dz$$

$$\omega_1 \wedge \omega_2 = -(\omega_2 \wedge \omega_1) \Rightarrow \omega \wedge \omega = 0$$

$$(\omega_1 + \omega_2) \wedge \omega_3 = (\omega_1 \wedge \omega_3) + (\omega_2 \wedge \omega_3)$$

$$(f(x, y, z) \omega_1) \wedge \omega_2 = f(x, y, z) (\omega_1 \wedge \omega_2)$$

$$\begin{array}{ccc} \vec{V}_1 \begin{vmatrix} P_1 \\ Q_1 \\ R_1 \end{vmatrix} \wedge \vec{V}_2 \begin{vmatrix} P_2 \\ Q_2 \\ R_2 \end{vmatrix} & = & \vec{V}_1 \wedge \vec{V}_2 \begin{vmatrix} X \\ Y \\ Z \end{vmatrix} \end{array} \quad \begin{array}{l} X = (dy \wedge dz)(Q_1 R_2 - Q_2 R_1) \\ Y = (dz \wedge dx)(R_1 P_2 - R_2 P_1) \\ Z = (dx \wedge dy)(P_1 Q_2 - P_2 Q_1) \end{array}$$

$$\omega = (dx \wedge dy)(P_1 Q_2 - P_2 Q_1) + (dy \wedge dz)(Q_1 R_2 - Q_2 R_1) + (dz \wedge dx)(R_1 P_2 - R_2 P_1)$$

$$\left(\frac{\partial \vec{M}}{\partial \alpha} \wedge \frac{\partial \vec{M}}{\partial \beta} \right) = \left(\frac{\partial \vec{M}}{\partial u} \wedge \frac{\partial \vec{M}}{\partial v} \right) \left(\frac{\partial u}{\partial \alpha} \frac{\partial v}{\partial \beta} - \frac{\partial u}{\partial \beta} \frac{\partial v}{\partial \alpha} \right)$$

Formule de Green Rieman :

$\varphi^+ = \text{courbe fermée}$ $\Delta = \text{domaine intérieur à } \varphi$

$$\int_{\varphi^+} (P_1(x, y) dx + Q_1(x, y) dy) = \iint_{\Delta} \left(\frac{\partial Q_1}{\partial x} - \frac{\partial P_1}{\partial y} \right) dx dy$$